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Mechanism and Machine Theory

journal homepage: www.elsevier.com/locate/mechmt



Corrigendum

Corrigendum to “Kinematic design of a non-parasitic 2R1T parallel mechanism with remote center of motion to be used in minimally invasive surgery applications” [Mechanism and Machine Theory 153 (2020) 104013]

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The authors regret that one of the affiliation information for Gökhan Kiper is wrong. Dr. Kiper is not affiliated to Delft University of Technology. Dr. Kiper is affiliated to İzmir Institute of Technology.

The data administrators of Elsevier and the corresponding author would like to apologise for any inconvenience caused.

DOI of original article: <https://doi.org/10.1016/j.mechmachtheory.2020.104013>.

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<https://doi.org/10.1016/j.mechmachtheory.2021.104514>

Available online 14 August 2021

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